

# **NOAA COASTAL MAPPING PROGRAM PROJECT COMPLETION REPORT**

## ***PROJECT NC0801A***

### ***Cape Henry to Corolla, Virginia and North Carolina***

#### **Introduction**

Coastal mapping project NC0801A, located in southeastern Virginia (VA) / northeastern North Carolina (NC), extends from Cape Henry in the north to Corolla in the South. The project includes Linkhorn Bay, Lake Rudee, and other lakes and backshore areas of Currituck Sound. The approximate bounding coordinates are 36° 22' to 36° 56' latitude, and 75° 49' to 76° 02' longitude. The project is part of the larger NC0801 acquisition project that extends from Cape Henry, VA to Cape Hatteras, NC.

Successful completion of this project resulted in a densification of the National Spatial Reference System (NSRS), a set of controlled metric-quality aerial photographs, airborne topographic LIDAR data, and digital feature data of the coastal zone which complements the Nautical Charting Program (NCP) as well as geographic information systems (GIS) for a variety of coastal zone management applications.

#### **Project Design**

The Requirements Branch (RB) of the Remote Sensing Division (RSD) formulated the photographic mission instructions for this project supplementary to the Photo Mission Standard Operating Procedure Version II (7/1/1993), the GPS Controlled Photogrammetry Field Operations Manual (1/2/1996), and the Light Detection And Ranging (LIDAR) Requirements Version 5 (7/3/2003). The instructions discussed the project's purpose, geographic area of coverage, scope and priority; photographic and LIDAR requirements; flight line priority; Global Positioning System (GPS) data collection procedures and guidelines for both kinematic and static surveys; data recording and handling instructions; and contact and communication information. RB created a Project Layout Diagram, flight maps and input files for the aircraft flight management system.

#### **Field Operations**

The field operations consisted of acquisition of aerial LIDAR data, digital aerial imagery, static and kinematic Global Positioning System (GPS) data, and Inertial Measurement Unit (IMU) data. Static GPS data were collected to support aerial data collection and processing operations as well as to assess the accuracy of post-processed imagery and LIDAR products.

The airborne survey operations were conducted March 17-26, 2008 with the NOAA Cessna Citation (N52RF). Ten strips of natural color digital images were acquired at a flying height of 1,500 meters, for a nominal ground sample distance (GSD) of 0.17 meters with an Applanix Digital Sensor System (DSS-439). Additionally, tandem strips of LIDAR data were collected,

using an Optech ALTM 3100 Topographic LIDAR sensor, for those areas corresponding to the outer coastline. LIDAR postings were collected at a nominal density of 1 posting per square meter.

### **Airborne GPS/IMU Data Processing**

GPS and IMU data were processed by RSD personnel to yield precise camera positions and orientations in order to provide a control network necessary for aerotriangulation. A local fixed base station at Newport News International Airport (PHF1) and a CORS station (NCPI, Pea Island) were used as base data for the GPS/IMU post-processing. The airborne kinematic data was processed using Applanix POSPAC (ver. 4.4) software in March-April of 2008. An Airborne Positioning and Orientation Report was written and is on file with other project data within the RSD Applications Branch (AB) Project Archive.

### **Ortho-image Processing**

Ortho-images were created with the DSS-439 imagery and associated image Exterior Orientation (EO) data using Applanix RapidOrtho software. United States Geological Survey (USGS) National Elevation Data (NED) were utilized as models to rectify the data.

Multiple field-surveyed check points were established using static GPS positioning methods, to assess the accuracy of the orthoimage data. Fifty (50) check points were surveyed in the Virginia Beach, VA area and twelve (12) check points were surveyed in the Frisco, NC area. Using these check points, the accuracy of the ortho-images was computed to be 2.0 meters circular error at the 95% confidence level (CE95).

### **LIDAR Data Processing**

LIDAR point cloud data were processed using the combined chain of:

- 1) Optech's *Project Dashboard* pre-processing software to place the LIDAR point cloud into a mapping projection,
- 2) Terrasolid's suite of LIDAR calibration and editing software to correct alignment, remove erroneous returns, and classify bare earth points,
- 3) NOAA's VDatum software to convert the vertical datum of the bare earth points from NAVD88 to local MHW, and
- 4) GeoCue LIDAR processing software to produce MHW digital elevation models (DEM) at 1m pixel resolution.

The journal article "Lidar-Derived National Shoreline: Empirical and Stochastic Uncertainty Analyses" (2010), published in the *Journal of Coastal Research*, contains more detailed information, and is on file in the RSD Project Archive.

### **Aerotriangulation**

The aerotriangulation (AT) task was initiated by RSD personnel in August of 2010 utilizing a Digital Photogrammetric Workstation (DPW). Image measurements and block adjustments were performed using BAE Systems' SOCET SET (SS, version 5.4.1) photogrammetric software. AT procedures were accomplished using the Multi-Sensor Triangulation (MST) module of SS. The Automatic Point Measurement (APM) algorithm, within MST, was used to collect tie points, and

a simultaneous solve adjustment was then performed. The predicted horizontal circular error, using all measured image points, was computed to be 0.3 meters at the 95% confidence level (CE95). Positional data for this project is referenced to the North American Datum of 1983 (NAD 83). An Aerotriangulation Report was written and is on file with other project data within the RSD Project Archive.

## Compilation

The data compilation phase of this project was performed between September 2009 and November 2010 and was performed in the following three distinct technical phases:

- 1) *LIDAR MHW Shoreline approach* – A MHW shoreline vector (in shapefile format) for the outer coastline, from Cape Henry to Corolla, was delineated using the MHW DEM discussed above and a Raster-to-Vector (R2V) script implemented within ESRI's ArcGIS 9.3 software. The shapefile table was then edited to create attribute fields compatible with the RSD interim shapefile format. Subsequently, the ortho-images were used to review/edit/attribute the LIDAR shoreline vector. The LIDAR shoreline was limited to sandy, natural MHW shoreline features along the outer Atlantic Ocean coastline and to a small portion of the Rudee Inlet – to include the seaward jetties along the approaches to the inlet. LIDAR was not utilized to delineate engineered features such as bulkheads, piers, bridges, or the backshore areas of Currituck Sound.

The LIDAR shoreline was compared to higher accuracy field transects, acquired at three (3) sample sites in the project area. Based on this comparison, the LIDAR derived shoreline vectors meet a horizontal accuracy of 4.5 meters at the 95% confidence level. This procedure is described in fuller detail in the journal article referenced above.

- 2) *Semi-Automated Feature Extraction (AFE) approach* – For compilation of the backshore marshes, an AFE method was performed using the ortho-images discussed above in combination with an object-based image analysis approach from within the ENVI Feature Extraction (Fx) software. ENVI Fx allows the user to interactively create and classify objects, based on image rules that meet in-situ criteria, and then run a R2V algorithm to convert the classified objects to an ArcGIS polygon shapefile. Upon completion of the AFE process, the polygon shapefile was imported into ArcGIS and 1) *aggregated* to merge polygons separated by less than the standard minimum distance, 2) *converted* to a polyline format, 3) *smoothed* and *simplified*, and 4) *edited* to create attribute fields (within the table) compatible with the RSD interim shapefile format. As in the LIDAR phase, ortho-images were used to review/edit/attribute the AFE shoreline vectors. The AFE shoreline was limited to marsh shorelines in the backshore areas of Currituck Sound.

Features compiled from the AFE method meet a horizontal accuracy of 2.0 meters at the 95% confidence level, as stated above in the Ortho-image Data section.

Note: The shape files, created in phases 1 and 2 above, were *merged* within ArcGIS to create a single shapefile in the RSD interim format. This *merged* file was then imported into SS and a

Feature Database (FDB) was created. The FDB, consisting solely of shoreline features (MHW and marsh), was then reviewed and edited within the SS Feature Extraction module, by the original compiler, using stereo-models derived from the AT solution.

- 1) *Stereo-Models and Manual Compilation approach* – The FDB, created above, was subsequently populated with additional features compiled using the SS Feature Extraction software module in combination with stereo-models. This served to integrate all coastal features within a single FDB. This manual data compilation phase utilized the *traditional* RSD digital mapping approach of stereoscopic interpretation integrated with “heads-up” digitizing.

Features digitized manually from the stereo-models were compiled to meet a horizontal accuracy of 0.6 meters at the 95% confidence level (CE95), calculated by doubling the circular error derived from AT statistics.

Feature attribution, for all three phases above, was assigned in compliance with the Coastal Cartographic Object Attribute Source Table (C-COAST), which provides the definition and attribution scheme for the full range of cartographic features pertinent to the CMP. Selected features were further modified with additional descriptive information to refine general classification.

The following table provides information on aerial photographs used in the project completion. See Appendix A, below, for tide information.

Date	Strip	Frames	GSD
3/17/2008	125093	17987-18185	0.17 m
3/17/2008	125094	19091-19292	0.17 m
3/18/2008	125097	20234-20412	0.17 m
3/18/2008	125098	20516-20550	0.17 m
3/21/2008	125095	21062-21263	0.17 m
3/25/2008	125096	22533-22735	0.17 m
3/26/2008	125117	23437-23496	0.17 m
3/26/2008	125119	23704-23732	0.17 m
3/26/2008	125120	24160-24168	0.17 m
3/26/2008	125118	24442-24505	0.17 m

## Quality Control / Final Review

Quality control tasks were conducted during all phases of project completion by a senior member of AB. Final QC review was completed in December 2010, including analysis of aerotriangulation results, assessment of the spatial placement of the LIDAR and AFE derived shorelines from within the stereo viewing environment, and assessment of the identification and attribution of digital feature data within the GC according to image analysis and criteria defined

in C-COAST. The quality control process concluded with an inspection of topological connectivity within the GC using ArcGIS 9.3 software. All project data was evaluated for compliance to CMP requirements.

Comparisons of the largest scale NOAA nautical charts with color imagery and compiled project data resulted in creation of the Chart Evaluation File (CEF). The following nautical charts were used in the comparison process:

- 12205, Cape Henry to Pamlico Sound (various scales), 31<sup>st</sup> ed., Dec. /07
- 12207, Cape Henry to Currituck Beach Light, 1: 80,000 scale, 21<sup>st</sup> ed., Mar. /04
- 12208, Approaches to Chesapeake Bay, 1:50,000 scale, 12<sup>th</sup> ed., May /07
- 12222, Cape Charles to Norfolk Harbor, 1:40,000 scale, 52<sup>nd</sup> ed., Sep. /09
- 12254, Cape Henry to Thimble Shoal Light, 1:20,000 scale, 48<sup>th</sup> ed., Mar. /09

## **End Products and Deliverables**

The following specifies the location and identification of the products generated during the completion of this project:

### **RSD Applications Branch Archive**

- Hardcopy of the Airborne Positioning and Orientation Report (APOR)
- Hardcopy of the Aerotriangulation (AT) Report
- Hardcopy of the Project Completion Report (PCR)
- Page-size graphic plot of GC10843 file contents, attached to PCR
- Hardcopy of journal article, "Lidar-Derived National Shoreline: Empirical and Stochastic Uncertainty Analyses" by White et al

### **Remote Sensing Division Electronic Data Library**

- Project database
- GC10843 in shapefile format
- Digital copy of the PCR in Adobe PDF format
- CEF in shapefile format

### **NOAA Shoreline Data Explorer**

- GC10843 in shapefile format
- Metadata file for GC10843
- Digital copy of the PCR in Adobe PDF format

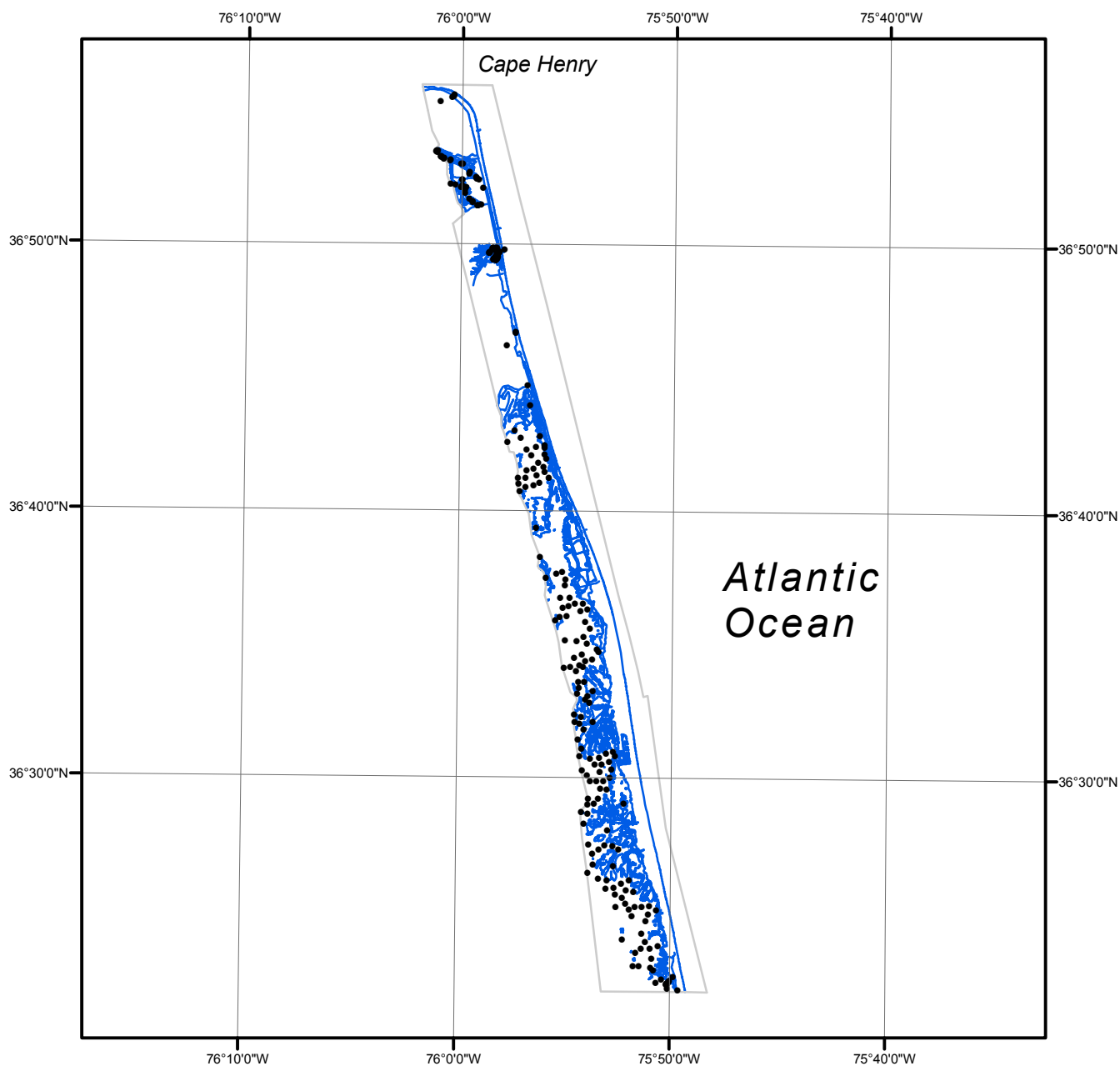
## **End of Report**

Tide Zone	Tide Station	Tide Range (in meters at reference station)	Day	Time (GMT)	Strip	Frames	Tide Level (in meters)
Outer Coast	Substation SANDBRIDGE from reference station DUCK	1.03 m	18-Mar	17:10	98	20516 - 20550	0 m
			18-Mar	16:50	97	20234 - 20412	0 m
			25-Mar	20:15	96	22648 - 22735	0.1 m
			25-Mar	20:08	96	22534 - 22582	0.1 m
Cape Henry	Substation CAPE Henry from reference station DUCK	1.03 m	17-Mar	18:00	94	19289 - 19292	0.2 m
			17-Mar	16:00	93	17987 - 17989	0 m
			21-Mar	13:40	95	21062 - 21067	0.9 m
Linkhorn Bay	Substation BROAD BAY CANAL EAST from reference station CHESAPEAKE TUNNEL	0.82 m	17-Mar	18:00	94	19263 - 19276	0.05 m
			17-Mar	16:00	93	18000 - 18017	0.15 m
			21-Mar	13:40	95	21079 - 21091	0.4 m
Currituck Sound	Substation ROANOKE SOUND CHANNEL from reference station OREGON INLET	0.31 m	17-Mar	16:00	93	18036 - 18185	0.02 m
			17-Mar	18:00	94	19091 - 19243	0 m
			21-Mar	13:45	95	21111 - 21263	0.15 m
			25-Mar	20:10	96	22583 - 22667	0.05 m
			26-Mar	14:50	117	ALL	0.07 m
			26-Mar	16:20	118	ALL	0.10 m
			26-Mar	15:10	119	ALL	0.07 m
			26-Mar	15:50	120	ALL	0.09m

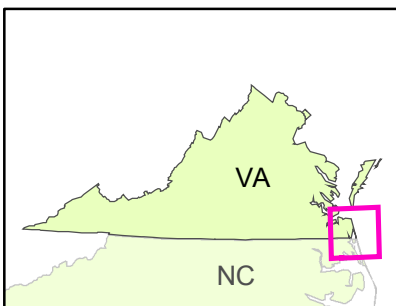
## Appendix A. Tide Data

# CAPE HENRY TO COROLLA

## VIRGINIA AND NORTH CAROLINA



Overview



NC0801A

GC10843